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17 Vegetation phenology can be captured with digital repeat

- photography and linked to variability of root nutrition in Hedysarum
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ABSTRACT

- Question: Can repeat (time-lapse) photography be used to detect the phenological development of a
- 59 forest stand, and linked to temporal patterns in root nutrition for *Hedysarum alpinum* (alpine
- sweetvetch) an important grizzly bear food species?
- 61 Location: The eastern foothills and front ranges of the Rocky Mountains in Alberta, Canada. The area
- contains a diverse mix of mature and young forest, wetlands, and alpine habitats
- 63 Methods: We deployed six automated cameras at three locations to acquire daily photographs at the
- 64 plant and forest stand scales. Plot locations were also visited on a bi-weekly basis to record the
- 65 phenological stage of H.alpinum and other target plant species, as well as to collect a root sample for
- determining crude protein content.
- Results: Repeat photography and image analysis successfully detected all key phenological events
- 68 (i.e., green-up, flowering, senescence). Given the relation between phenology and root nutrition, we
- 69 illustrate how camera data can be used to predict the spatial and temporal distribution and quality of a
- 70 key wildlife resource.
- 71 Conclusions: Repeat photography provides a cost effective method for monitoring vegetation
- development, food availability, and nutritional quality at a forest stand scale. Since wildlife responds to
- 73 the availability and quality of their food resources, detailed information on changes in resource
- 74 availability helps with land use management decisions and furthers our understanding of grizzly bear
- 75 feeding ecology and habitat selection.

1. INTRODUCTION

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Seasonal changes in vegetation phenology are critical drivers of food availability and quality for a wide 78 79 variety of animal species. Food availability affects large-scale movements in migratory species such 80 as caribou (Festa-Bianchet et al., 2011; Sharma et al., 2009), as well as the seasonal foraging habits of species within their home ranges (Nielsen et al., 2003; 2010). This is the case for grizzly bears 81 82 (Ursus arctos), which are considered generalists with diverse diets that change during the course of the year. Individual bears may travel large distances to locate high quality food sources (Rogers, 83 1987) with a diet comprised of seasonally abundant and nutrient rich food (Hamer and Herrero, 1987; 84 Hamer et al., 1991; Craighead et al., 1995; McLellan and Hovey, 1995; Munro et al., 2006). Within 85 their remaining range in western Canada, grizzly bears have three distinct foraging seasons: 86 hypophagia, early hyperphagia, and late hyperphagia (Nielsen et al., 2006). During hypophagia, 87 grizzly bears feed on the roots of *Hedysarum* spp. (sweetvetch) and other early herbaceous material. 88 89 During early hyperphagia, their diet extends to green herbaceous material such as Heracleum lanatum (cow-parsnip) and Equisetum spp. (horsetail), while in the later season berries such as Shepherdia 90 91 canadensis (buffalo berry) and Vaccinium spp. (huckleberry, blueberry and lingonberry) make up the 92 majority of their diet. As fruit consumption declines in the fall, grizzly bears once again dig for 93 sweetvetch roots (Nielsen, 2005; Nielsen et al., 2006; Munro et al., 2006; Nielsen et al., 2010). While 94 animal matter and insects are an important food resource for grizzly bears during spring and early 95 summer, the wide variety of vegetable matter, including roots, forbs and fruit, makes up the majority of 96 their diet from late June through to early October. The amount of animal matter consumed by grizzly 97 bears can also vary by season (moose and other ungulate calves), distribution and abundance (Munro 98 et al.2006). In previous work (Bater et al., 2011a,b; Coops et al., 2012) the role of digital cameras in monitoring 99 100 vegetation phenology across a range in grizzly bear habitats of Alberta has been demonstrated. 101 Camera images provide an alternative to traditional assessment of phenology that rely on field 102 observations, often by seasonal workers, volunteers and amateur naturalists, who record discrete 103 events such as flowering, leaf emergence, and other characteristics depending on observation goals and site location (Crimmins et al., 2008; Studer et al., 2007). While these observations are a valuable 104 105 source of information, they are limited in spatial coverage, are often based on varying methodologies and conducted by many observers with different training and skill levels resulting in data 106 inconsistencies. Repeat photography using ground based cameras (i.e., near sensing (Jongschaap 107 and Booij. 2004)) to monitor vegetation phenology allows for very fine temporal sampling (e.g., at daily 108 109 or hourly intervals) in a consistent and cost-effective manner. In fact, near sensing of vegetation phenology is dramatically increasing in popularity across a diverse range of disciplines including, 110 111 agriculture (Purcell, 2000; Karcher and Richardson, 2003; Zerger et al., 2010), plant ecology (Ide and

Oguma, 2010; Graham et al., 2010; Kurc and Benton, 2010) and forestry (Ahrends et al., 2008; Polgar 112 113 and Primack, 2011; Sonnentag et al., 2012). However, many of these studies focus on either linking 114 distributed cameras into networks to follow phenological development at national or continental scales 115 (Jacobs et al., 2009; Graham et al., 2010; Ide and Oguma, 2010) or observations of a single plant or plot (Karcher and Richardson, 2003; Sonnentag et al., 2012). 116 117 By mounting camera systems on towers, trees or platforms, data can be acquired at an intermediate scale of observation, providing a link between field-based observation methods and satellite derived 118 119 estimates (Hufkens et al., 2012). Bater et al.(2011b) confirmed that spectral indices derived from these 120 camera systems relate significantly to field observations of both the green-up and senescence of vegetation, with mean absolute differences in residuals between the predicted and observed dates of 121 122 green-up and length of growing season reported as four days and six days, respectively. These measures of vegetation phenology from ground-based cameras also significantly relate to satellite-123 derived measures of greenness (Coops et al., 2012). 124 125 Despite the demonstrated capacity to monitor vegetation phenology remotely, changes in vegetation 126 greenness detected by cameras do not necessarily directly correspond to other factors affecting use of 127 those resources such as nutrient quality. For example, in the case of grizzly bears the nutritional 128 content of Hedysarum alpinum (alpine sweetvetch) roots varies significantly throughout the growing 129 season, with its highest nutritional concentration occurring prior to and during the initial green-up phase (Hamer et al., 1991; Coogan et al., 2012). Once the above ground biomass component of 130 131 H.alpinum has reached its peak, corresponding to the mid-point of the growing season, the nutritional value of the roots substantially decreases when compared to the initial green-up earlier in the season 132 or senescence in the fall (Coogan et al., 2012). As a result there is a need to link remote sensing 133 derived observations of greenness to not only vegetation activity, but also to the nutritional value of the 134 above and below ground components of the vegetation. 135 The main objectives of this study are twofold. First, examine changes in vegetation phenology of key 136 137 individual plant species critical to grizzly bear diet using very high spatial resolution digital camera data. Changes in vegetation phenology (spectral greenness) for individual plants were examined over 138 a full growing season and compared to phenophase observations of the above ground vegetation 139 component, as well as to the nutritional content of the below ground roots. The second objective of the 140 study is to demonstrate if individual species-based models, such as *H.alpinum*, can be scaled up 141 using stand scale digital camera observations. If these relationships exist, then the distribution and 142

timing of forage availability can be predicted at broader scales.

2.1 Study Area

The focus of this study was the foothills in western Alberta, Canada. The area contains a diverse mix of mature and young forest, wetlands, and alpine habitats. Three sample sites were located near the towns of Robb and Cadomin, Alberta (53.2°N; 117.0°W) in order to observe the range of phenological changes and growing season conditions across known grizzly bear habitat. At each site a pair of cameras were installed with different fields of view (see camera setup section below), one camera focused on individual plants (plant scale), while the second camera focused on the forest stand (stand scale). Details on the sites, their vegetation composition, and location are summarized in Table 1.

Table 1: Characteristics of the camera plot locations

Plot	Coordinates [UTM 11N]	Elevation [m]	Vegetation Type
Drinnan Creek	N5894401; E465076	1356	Spruce and pine forest
Folding Mountain	N5900474; E447823	1139	Spruce forest
Cardinal Divide	N5860769 ; E483439	2025	Alpine meadow

2.2 Digital Camera Setup

Six standard commercially available digital camera systems manufactured by Harbortronics (Gig Harbor, Washington, USA) were installed at the three sites. The camera systems include a Pentax K100D digital SLR camera mated to an intervalometer. The camera was sealed in a fiberglass case with a solar panel and lithium ion battery to provide power. At each of the three plots, one camera was mounted three metres above the ground on a tall and dominant tree and pointed north (as described in Bater et al., 2011a) with images capturing conditions of the forest stand (Figure 1, right). A second camera was mounted close to the first camera, but with a reduced field of view (approximately 5 x 5 m) in order to monitor a small number of individual plants (Figure 1, left), hereafter referred to as the plant scale. To minimize directional effects caused by solar movements, all cameras acquired five images per day between noon and 13:00 local time at regular intervals. Digital images were archived as full resolution JPEG files (3008 x 2008 pixels) and ancillary data included a time stamp for easy reference of date of acquisition.



Figure 1: Example images at the plant scale (left) and forest stand scale (right) taken at the Cardinal Divide site near Cadomin, Alberta. Both images taken at 15 July 2010.

2.3 Field validation, phenophase codes and root nutrition data

 Two sets of imagery acquired at the three sites provided a range of homogenous understorey and overstorey species-specific regions of interest, observable on the digital camera imagery. All sites were visited weekly between April and October 2010 to record the phenophase codes (Table 2) of the vegetation following the practices of Dierschke (1972). In the further analyses we use summarized phenological scale with pre-leaf: Vegetative ≤ 4, leaf: Vegetative ≥ 5, flower: Reproductive ≥ 6, seed: Reproductive ≥ 10, and dormant: Vegetative ≥ 9 (Table 2). The green-up, flower, and senescence dates are defined as the first occurrence of leaf, flower and dormant respectively. Observable species included *Hedysarum alpinum* (alpine sweetvetch), *Sheperdia canadensis* (buffalo berry), *Lathyrus ochroleucus* (cream pea), *Vaccinium vitis-idaea* (lingonberry), *Arctostaphylos uva-ursi* (Bearberry), and *Dryas octopetala* (mountain avens). In addition to the phenophase observations *H.alpinum* plants just outside of the observable images were also sampled for nutritional content. In total, 66 samples were collected and analysed for crude protein content following the procedures described in Coogan et al. (2012). All protein measurements were normalized as a fraction of the total dry matter. To allow comparisons between the camera information, phenology data, and root protein data, root samples were grouped into five phenological stages (pre-leaf, leaf, flower, seed, and dormant).

Vegetative

- 0. Closed bud
- 1. Green leaf out but not unfolded
- 2. Green leaf out, start of unfolding
- 3. Leaf unfolding up to 25%
- 4. Leaf unfolding up to 50%
- 5. Leaf unfolding up to 75%
- 6. Full leaf unfolding
- 7. Stem / first leaves fading
- 8. Yellowing up to 50%
- 9. Yellowing over 50%
- 10. Dead

Reproductive

- 0. Without blossom buds
- 1. Blossom buds recognizable
- 2. Blossom buds strongly swollen
- 3. Shortly before flowering
- 4. Beginning bloom
- 5. Up to 25% in blossom
- 6. Up to 50% in blossom
- 7. Full bloom
- 8. Fading
- 9. Completely faded
- 10. Bearing green fruit
- 11. Bearing ripe fruit
- 12. Bearing overripe fruit
- 13. Fruit or seed dispersal



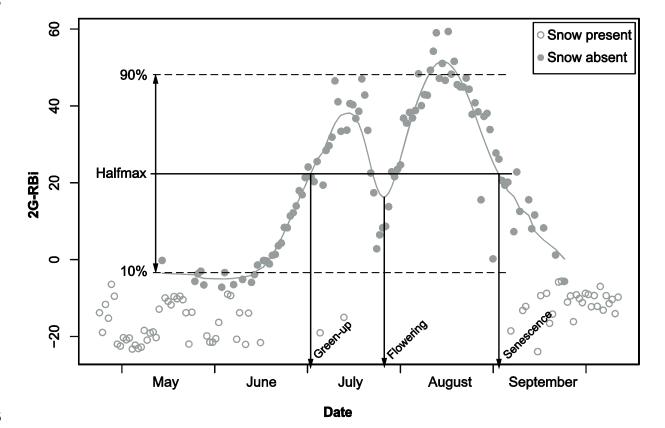


Figure 2: Seasonal metrics calculated from the 2G-RBi time-series from each pixel.

198 2.4 Image Analysis:

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199 As discussed in Bater et al (2011a), a number of approaches exist to extract phenological information from a time series of remotely sensed spectral data. Information on key dates, such as green-up and 200 201 senescence, has precedence in the literature (e.g. Waring et al., 2006). In our case, to extract the 202 phenological response from the image sequences, the five images collected each day were averaged into a single daily scene to reduce the effects of differential exposure and shading in the images. 203 204 These daily averages were then filtered a 4 x 4 mean kernel to reduce data volumes and the effects plant parts moving in the time between images caused by plant growth or more notably wind. 205 206 In order to extract a single spectral index indicative for vegetation activity from the blue, green and red spectral channels we calculated the 2G-RB index (Richardson et al., 2007), hereafter noted as 2G-207 RBi. The 2G-RBi compares the green channel of the RGB image to the red and blue channels to 208 derive excess greenness corrected for illumination differences: 209

$$2G_{R}B_{i} = 2\mu_{G} - (\mu_{R} + \mu_{B}),$$
 [1]

where μ_G , μ_R and μ_B are the camera observed brightness values (image DN) in the green, red and 211 blue channels, respectively. All images where snow was present in the scene were removed from 212 further analysis and a smoothing spline with rigidity of 2/3 was fitted to the 2G-RBi data for each pixel similar to that of Richardson et al. (2009). Key dates from the fitted spline were then extracted 214 215 including date of green-up, end of season, and flowering of the *H.alpinum* (Figure 2). To do so, greenup was defined as the first date the greenness was higher than that pixels robust halfmax (90th 216 percentile – 10th percentile / 2); scenescence was defined as the last date the greenness was higher 217 than that pixels robust halfmax. The robust halfmax was chosen above a standard halfmax or inflexion point to account for the greater amount of scattering present in the by-pixel data as opposed to 220 analysis of averages over larger pre-defined areas. The halfmax is commonly used to detect the dates 221 of start of season in camera (Richardson et al., 2009, Bater et al., 2011a), or satellite based phenology 222 detection (Schwartz et al., 2002) Flowering of H.alpinum was detected as a local minimum in the greenness curve between the green-up date and the end of season. This minimum is caused by the 224 pink flowers of *H.alpinum* that have a negative 2G-RBi.

225 2.5 Landscape forage quality

Based on the derived relationship between phenological development and root protein content of H.alpinum we inferred the nutritional value available in the stand as derived from a time-series of the stand scale photographs. The clearly outstanding colour of the pink *H.alpinum* flowers allows for detection of this species over the stand, as the flowers have a negative greenness value. The

detected flowers are buffered in a 25 pixel radius excluding any bare areas to create a mask of *H.alpinum* plants. The area within this mask was used to derive the phenological development of *H.alpinum* through the growing season and the dates of green-up, flowering, and senescence for this species. The phenological events for *H.alpinum* as detected by the camera system is linked to underground root nutrition by the temporal relation between root crude protein content and aboveground phenology (Coogan et al., 2012). Repeat photography provides information on both the location of the species of interest (*H.alpinum*) and the timing of phenological events. The combination of the development and location provides insight in the availability of high quality forage on a landscape scale.

3. RESULTS

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- Approximately 850 images were obtained from each camera covering the period from mid-April to midOctober. Figure 3(A) provides an example of a typical field of view at the plant scale during flowering
 of *H.alpinum*. The image clearly shows the leaf structure and flowers of the plant. The 2G-RBi image
 is shown in Figure 3(B) with white areas indicative of very green vegetation and darker areas showing
 non-vegetated scene components. The derived start and end of growing season images are shown in
 Figure 3(C) and (D) respectively.
- 246 Camera-derived dates of phenological events and the field observed dates are strongly correlated (r² 247 = 0.89, p < 0.01, N=16), except for evergreen ericacaea shrubs (e.g., V. vitis-idea, A. uva-ursi) which 248 did not exhibit easily detectable changes in phenology or greenness and show up as clear outliers 249 below the 1:1 line (Figure 4). The relationship between the field measured phenophase and the protein content of *H.alpinum* is shown in Figure 5, and demonstrates the reduction in protein content 250 while plants are actively growing. The pre-leaf phenological stage had the highest nutritional value 251 252 while the flower and seed phenophases had the lowest nutritional values. Also apparent is the high 253 nutritional load of the below ground component when the species are dormant, and the variability of root protein across the 3 sites. 254

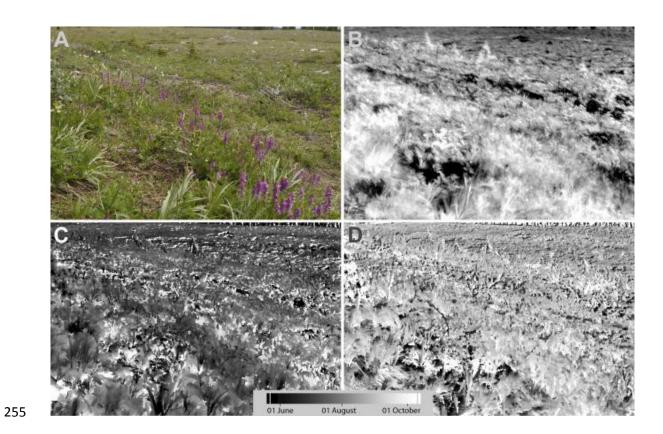
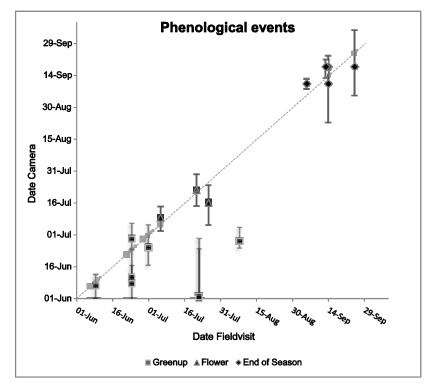


Figure 3: Examples of phenology camera data, A) RGB image, B) 2G-RB index image, C) Green-up,
D) Senescence.



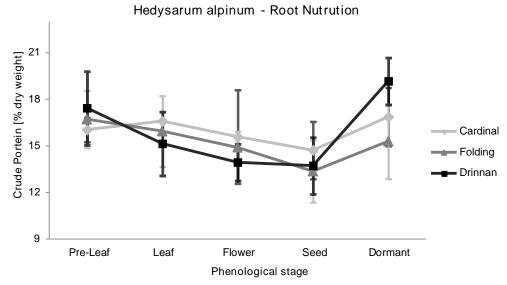


Figure 5: Average crude protein content of *H.alpinum* roots sampled in three locations in west-central Alberta, Canada in different phenological stages. Error bars are 1 standard error above and below the mean. Based on data from Coogan et al. (2012).

3.1 Landscape forage quality

Based on a time series of images at the forest stand scale, we detected both the spatial distribution and phenological development of *H.alpinum*. Figure 6 shows a forest stand scale photograph at the Cardinal divide site with areas marked in pink representing the area of *H.alpinum* plants. The temporal patterns of major phenological events in the cells containing *H.alpinum* are shown in Figure 7. Greenup starts halfway through June with the peak of growth two weeks later. Flowering lasts approximately three weeks, between mid-July and the first part of August. The decline of greenness starts around mid-August with all aboveground components senesced by mid-September.



Figure 6: Spatial pattern of presence of *H.alpinum*, masked in pink for the stand scale image collection at Cardinal Divide near Cadomin, Alberta.

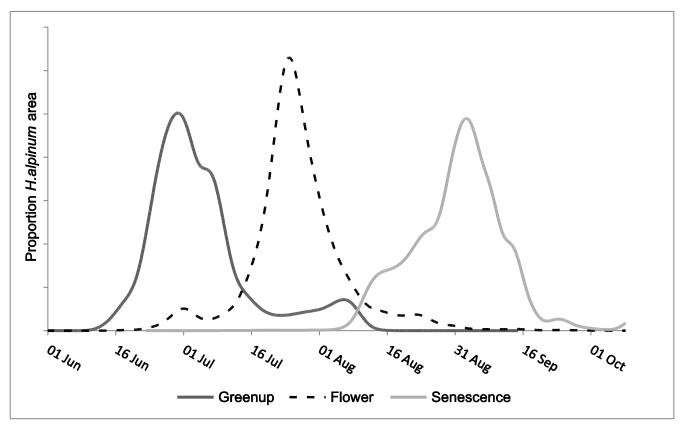


Figure 7: Histograms of Green-up, Flowering, and Senescence for H.alpinum from the Cardinal Divide stand scale camera perspective.

4. DISCUSSION

While broad scale patterns in phenology can provide an overall assessment of available food resources and inter-annual changes in forest productivity, a key limitation of working at this scale is the inability to detect subtle or species specific phenological events which occur at the temporal and spatial scale at which animals perceive their environment and are critical for food modelling (Nielsen et al., 2003; 2010). In this paper we use two sets of cameras configured to capture imagery at the plant-and forest stand scale. This paired design allowed the precise timing of initial leaf unfolding and the development of fruits to be observed and subsequently linked to the nutritional value of the belowground food resource. Placing cameras in close proximity to plants offers the advantage of continuous data and possibly reduced frequency of field visits for collection of phenological data (phenophase monitoring). This study confirms that ground-based cameras can be employed to simultaneously monitor phenology of multiple plant species within the image footprint, and that images capturing different scales can be linked with landscape assessments of vegetation nutrition. The phenological development of *H.alpinum* indicates that high protein roots were available before the start of July and again after the end of August (Coogan et al., 2012). This pattern corresponds well

with root consumption patterns as observed in grizzly bear feces (Munro et al., 2006) and GPS telemetry data on habitat selection (Coogan et al., 2012) which show most root consumption in late April to June, and resuming from August to October.

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From a wildlife management and monitoring point of view, we believe it is the linking of figures 5 and 7 in this work which provide the greatest insights. Whilst there is considerable variability around the root nutritional value at the sampled sites (initial high nutritional value, followed by a reduction at flowering and seed, and an increase again at dormancy), the pattern of nutritional status throughout the season is similar to many understory species. Most of these species allocate greater resources above ground for reproduction at certain times of the year, thereby reducing resources below ground and at other times, with few above ground resources to support at pre-leaf and dormant stages, the below ground component of the vegetation gains comparatively more resources and thus nutrient content. This pattern of below ground nutrient availably is the inverse of the camera observable greenness, and thus the link is an inverse one for forest managers. The portion of the scene shown in Figure 7 at each of the key, above ground phenological phases, can essentially be inversely multiplied by the nutritional value in Figure 5 to provide a landscape estimate of the nutrient carrying load of this specific vegetation type for wildlife. In this example at Cardinal divide, nutritional availability for food is highest between June 1st - July 1st (before maximum green-up) and after August 15th (during senescence). The capacity to provide explicit dates of when these maximum nutritional load events occur across the landscape is of significant benefit to managers as it provides key time periods when bear activity in these areas is most likely, or conversely least likely, to occur due to root forage quality and availability. While other food sources, and management activities, will of course also impact bear movements and locations, this information provides one key perspective on the overall bear landscape. Multiple cameras, at multiple sites, characterising the key bioclimatic zones across the region would, when combined, provide a region-wide bear forage availability map which could be updated in real time and provide an immediate perspective on the nutritional load for the bears within this area.

For the stand scale detection of forage availability, improvements can be made to the current camera setup. Because the cameras have a highly oblique view, only part of the image frame can be used for a reliable detection of phenological development in individual species. In areas far from the camera position, the spatial resolution is reduced. The potential to install the cameras with a field of view closer to nadir would decrease perspective issues as well as potentially provide better separation between taller and adjacent lower vegetation. However, such a setup would require a higher mounting point for the cameras and possibly installation on a mast or structure other than a tree which would increase deployment costs and reduce the area observed.

As this study demonstrates, unique challenges remain for detecting phenological events in evergreen species. Evergreen species show a less pronounced response in camera measured greenness and are therefore not reliably identified by the current system. An improved detection of the phenology of evergreen species may be provided by a modified camera system that detects changes in near infrared reflection which is known to be highly sensitive to changes in vegetation activity.

5. CONCLUSIONS

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In this paper we describe a system and approach to detect the phenological development of individual plant species from daily camera images at both a plant and forest stand scale. The phenological development of certain species is closely linked with the nutritional value of above and belowground parts of these plants, and therefore the availability of high quality forage for grizzly bear. The use of repeat photography provides a cost effective way to assess vegetation development and food availability at a forest stand scale, improving information availability for management of bear habitat and as a tool for increasing our understanding of grizzly bear feeding ecology.

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